



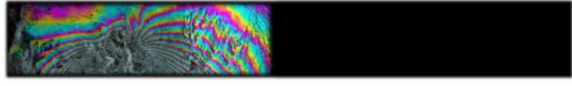
GEOS 657 – MICROWAVE REMOTE SENSING
GRADUATE-LEVEL COURSE AT THE UNIVERSITY OF ALASKA FAIRBANKS

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Lecture 14: On the Use of InSAR in Geophysics



UAF Course GEOS 657

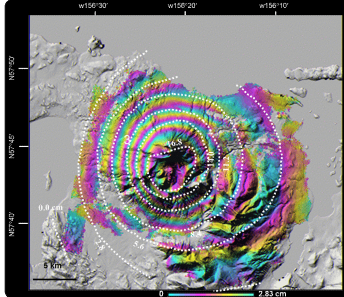



THE USE OF INSAR IN GEOPHYSICS




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InSAR Helps us Measure Surface Displacement
Example: Mt. Peulik volcano, Alaska



- InSAR gives us a geodetic measurement in the sense that it provides information about a pixels location in the world and about its movement.
- InSAR does not tell us WHY the surface is moving in the observed way.
- To determine the geophysical cause of the observed motion, we need to combine our InSAR observables with geophysical models



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The Deformation Modeling Problem

deformation:
what we see (InSAR)

magma dynamics:
what we want to know

Magma intrusion

The Deformation Modeling Problem

Estimate source characteristics from InSAR deformation data

forward model

design matrix

$$G \cdot s = d$$

source parameters displacement (vector)

inverse model

$$s = G^{inv} \cdot d$$

Solving for Model Parameters using Model Inversion

$G \cdot x = b$

- If the covariance matrix for errors in the observation (b) is Σ_b , then the weighted least-squares (maximum likelihood) solution for x is

$$\hat{x} = [G^T \cdot \Sigma_b^{-1} \cdot G]^{-1} \cdot [G^T \cdot \Sigma_b^{-1} \cdot b]$$
 and the covariance matrix for the estimated vector components is

$$\Sigma_x = [G^T \cdot \Sigma_b^{-1} \cdot G]^{-1}$$
- In the case where we assume that observation errors are independent and have equal standard deviations, σ , we get

$$\Sigma_x = \sigma^2 [G^T \cdot G]^{-1}$$
 - The square roots of the diagonal terms of Σ_x are the standard errors of the estimated parameters

What is the Forward Model in Volcano Deformation?

Predicts deformation (\underline{u}) caused by magma intrusion (relates magma intrusion to deformation)

$\underline{u} = f(\text{model parameters})$

elasto-static behavior

$$\mu \nabla^2 u_i + \frac{\mu}{(1-2\nu)} \left[\frac{\partial^2 u_k}{\partial x_i \partial y_k} \right] = -F_i$$

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What is the Forward Model?

Simple Model: Inflating Point Source Model

- A component of deformation vector (u_i) and the displacement at the free surface ($x_3 = 0$) takes the form

$$u_i(x_1 - x'_1, x_2 - x'_2, -x'_3) = C \frac{x_i - x'_i}{|R^3|}$$
 - x'_i is a source location, C is a combination of material properties and source strength, and R is the distance from the source to the surface location
- C is defined as follows:

$$C = \Delta P(1 - \nu) \frac{r_s^3}{G} = \Delta V \frac{(1 - \nu)}{\pi}$$

Unknown (target) parameters marked in red

 - ΔP - change in pressure of magma chamber
 - ΔV - change in volume of magma chamber
 - ν - Poisson's ratio (material property)
 - r_s - radius of the sphere
 - G - shear modulus of country rock (material property)

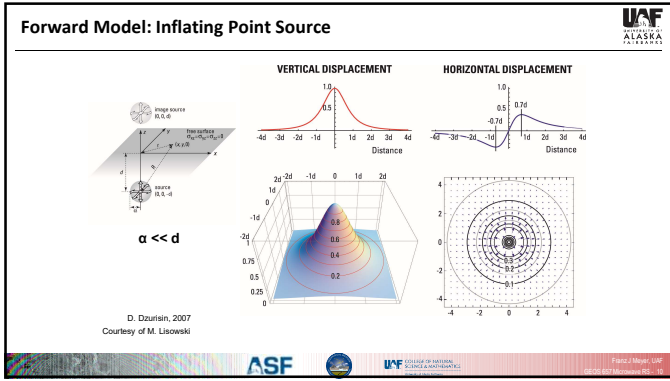
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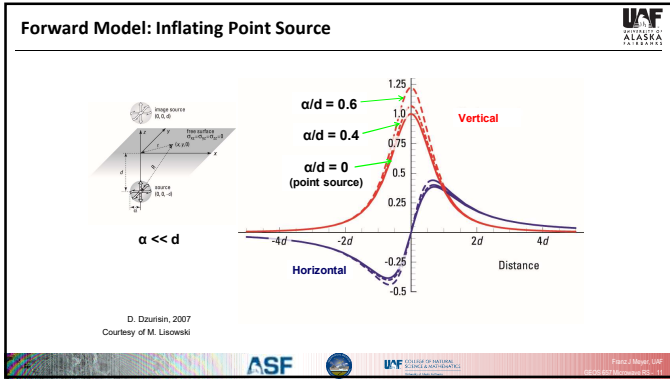
Think - Pair - Share:

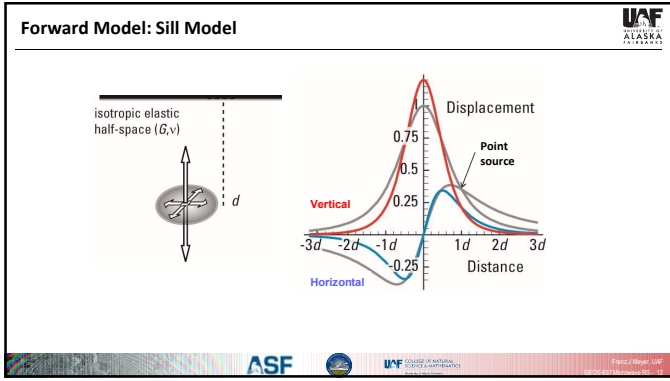
- Limitations of Mogi Models**
 - Let's look at the Mogi model equations one more time

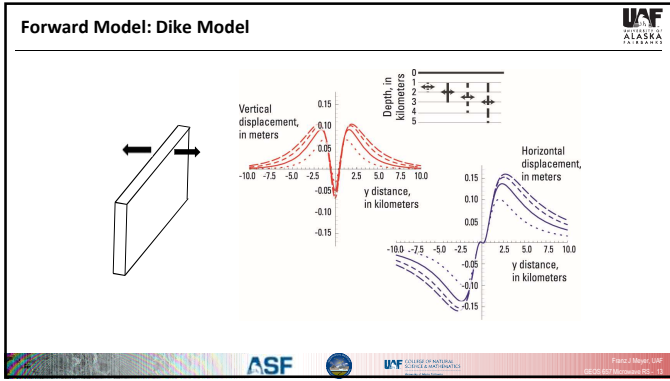
$$u_i(x_1 - x'_1, x_2 - x'_2, -x'_3) = C \frac{x_i - x'_i}{|R^3|} \text{ with } C = \Delta P(1 - \nu) \frac{r_s^3}{G} = \Delta V \frac{(1 - \nu)}{\pi}$$
 - Activity 1:** Discuss the limitations that may be brought on by how the variables ν and G are used in these equations.
 - Activity 2:** Discuss the limitations that may be brought on by how the source geometry is captured in the equations.

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Ultimate Goal of Deformation Modeling:

Minimize

$$\sum [u_i(x, y) \cdot los_i(x, y) - obs_i(x, y)]^2$$

u_i is a theoretical calculation of ground surface deformation vector (i=1, 2, 3)
 los_i is the InSAR line-of-sight vector
 obs_i is the observed deformation (InSAR image)
 (x, y) is the image coordinate

Non-linear inversion!!!!

Find the best-fitting Model Parameters

Grid Search: A Simple Approach


1. Loop through model parameters
2. calculate the residual (observed – modeled) for each set of model parameters
3. Find the set of model parameters that renders the smallest residual

→ best-fitting model parameters

Next Week: A Jupyter Notebook Lab for Estimating Source Parameters

What we will do in the lab:

- We will define a search space for source model location
- We will assume that source depth and magma volume change are known and fixed
- For each set of *x* and *y* coordinate parameters:
 - We will run a forward model to produce predicted surface deformation results
 - Calculate difference (residuals) between predicted and measured deformation
- Best fitting model parameters are those that minimize residuals between observations & model prediction

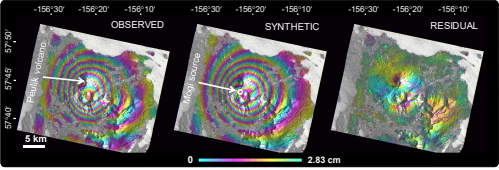


Z (depth)

ΔV (volume change)

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Mt. Peulik Example



- Spherical Point Source Model (Mogi Source)

$$u_i(x_1 - x'_1, x_2 - x'_2, -x'_3) = C \frac{x_i - x'_i}{|R|^3}$$

Where x'_i is source location, C is a combination of material properties and source strength, and R is the distance from the source to the surface location
- Best fit Source parameters:
 - Depth: $6.5 \pm 0.2 \text{ km}$; Volume change: $0.043 \pm 0.002 \text{ km}^3$

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What's Next?

- This is what awaits next:

- Next: Lab on Mogi source inversion from InSAR

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