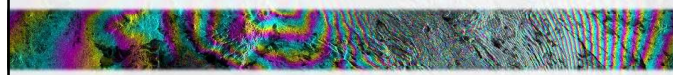


GEOS 657 – MICROWAVE REMOTE SENSING
GRADUATE-LEVEL COURSE AT THE UNIVERSITY OF ALASKA FAIRBANKS

Lecturer:
 Franz J Meyer, Geophysical Institute, University of Alaska Fairbanks, Fairbanks; fimeyer@alaska.edu

Lecture 16: The SBAS (Short Baseline Subset) Approach to InSAR Time Series Analysis



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BEFORE WE START ...



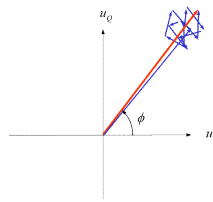
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Think – Pair – Share

Point Target-based InSAR time series techniques (e.g., PS-InSAR):


Activity 1: Point-Like Scatterers and Coherence:
 [Ferretti et al., 2001] found that pixels whose radar signal is dominated by one very bright and stable point-like scatterers tend to be coherent over very long times. Hence, in his PS-InSAR technique, Ferretti first identifies point-like targets using their amplitude signature and then analyzes their phase for high-accuracy deformation monitoring.

- Discuss why point-like scatterers with high and stable amplitude usually also have stable phase. Complete the sketch to the right in your discussion.

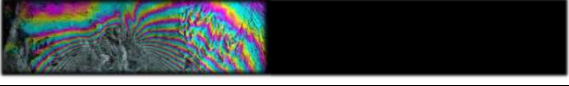


Activity 2: Limitations of PS-InSAR:
 While the point target-based PS-InSAR technique can provide highly accurate surface deformation information in urbanized environments, its performance is often limited when applied to natural environments (e.g., volcano deformation or permafrost subsidence)

- Identify least two reasons why PS-InSAR type techniques often underperform in natural setting?



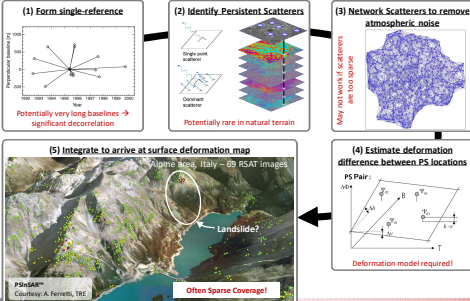
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A ONE-SLIDE RECAP OF THE POINT TARGET-BASED PS-INSAR TECHNIQUE

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The PS-InSAR Workflow
And its Limitations for Natural Terrain



(1) Form single-reference
Potentially very long baselines → significant decorrelation

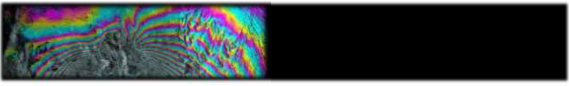
(2) Identify Persistent Scatterers
Potentially rare in natural terrain

(3) Network Scatterers to remove atmospheric noise
Why not work if scatterers are too sparse

(4) Estimate deformation difference between PS locations
Deformation model required!

(5) Integrate to arrive at surface deformation map
Often Sparse Coverage!

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SBAS - DISTRIBUTED TARGET-BASED INSAR TIME SERIES ANALYSIS

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Study Deformation Over Natural Terrain

Distributed Target InSAR

- + higher point density in natural terrain
- + flexible, easily applicable to large areas
- usually higher noise level
- averaging reduces resolution

Pepe et al., Time Series Analysis and Applications, 2018

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Natural Terrain

Distributed targets

- + widespread (pasture, bare soil, etc.)
- + coherence as quality measure
- averaging reduces resolution
- typically less stable: decorrelation

Two important sources of decorrelation

Temporal decorrelation
Sub-resolution scatterers change with respect to one another
Example: branches move in the wind

Spatial decorrelation
If difference in look angle (spatial baseline):
Individual returns add up differently

Spatial decorrelation not a major concern for Sentinel-1 and NISAR

Adapted from A. Hooper

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Short Baseline Subset InSAR

Original publication: Berardino, P. et al., (2002): "A new algorithm for surface deformation monitoring based on small baseline differential SAR interferograms," IEEE TGRS, 40(11), pp.2375-2383.

- Idea:** Form many high coherence interferograms by selecting a subset of interferograms with short spatial and moderate temporal baselines
- Advantages:**
 - More coherent information, especially in natural environments!
 - Large number of interferograms helps in mitigating processing errors and noise
- Concept sketch:**

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The Small Baseline Subset (SBAS) Method

A Word about Design Matrix A

- Matrix A describes how deformation history ϕ_{defo} maps into InSAR phase $\Delta\phi$

Example:

- $N = 4$ SAR acquisition times t_i at which ϕ_{defo} was sampled; $M = 6$ ifgrms ($\Delta\phi$)

We can write this problem as:

$$\begin{bmatrix} \phi_{defo}(t_2) - \phi_{defo}(t_1) \\ \phi_{defo}(t_3) - \phi_{defo}(t_1) \\ \phi_{defo}(t_4) - \phi_{defo}(t_1) \\ \phi_{defo}(t_4) - \phi_{defo}(t_2) \\ \phi_{defo}(t_4) - \phi_{defo}(t_3) \end{bmatrix} = A \cdot \begin{bmatrix} \phi_{defo}(t_1) \\ \phi_{defo}(t_2) \\ \phi_{defo}(t_3) \\ \phi_{defo}(t_4) \end{bmatrix}$$

Design matrix A :

$$A = \begin{bmatrix} -1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & -1 & 0 & 1 \\ -1 & 0 & 0 & 1 \end{bmatrix}$$

(Note: $M = 6$ rows, $N = 4$ columns)

The Small Baseline Subset (SBAS) Method

Design Matrix in SBAS Phase Inversion

Design matrix

Describes how the changing surface position is reflected in each interferogram

Example:

$N = 4$ images, $M = 6$ Interferograms

$$A = \begin{bmatrix} -1 & 0 & 0 & 1 \\ 0 & -1 & 0 & 1 \\ 0 & 0 & -1 & 1 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 1 & 0 \\ -1 & 1 & 0 & 0 \end{bmatrix}$$

(Note: $M = 6$ rows, $N = 4$ columns)

Interferogram phase $\phi_{2,1}$ contains the deformation between time 2 and time 1, i.e. $-\phi_1 + \phi_2$.

Parameterization

One can also include a deformation model and the DEM error here (how?)

Observations

Unknowns

The Small Baseline Subset (SBAS) Method

Uniqueness of Solution (advanced material)

Is there always a unique solution?

Problem 1: InSAR is a differential technique

Only sensitive to differences in path length such as deformations

What happens if you add a constant shift to ϕ ?

$\phi = A\phi$ does not change!

We say that A has a rank defect (or a non-trivial kernel or nullspace). The solution ϕ to the least-squares problem is not unique. We can make it unique by fixing e.g. ϕ_1 and referencing all deformation relative to this time instance. Then $\phi_{2,1}$, say, corresponds to a cleaned interferometric phase $\phi_{2,1}$ with reduced decorrelation noise but still contaminated by atmosphere etc.

Problem 2: Insufficient Interferograms

Can you spot the problem?

How would your measurements change if there was a shift to all the time instances in cluster 1?

This is another rank defect. One needs additional conditions or constraints to deal with it.

The Small Baseline Subset (SBAS) Method
 How to Calculate $\hat{\phi}_{defo}$ from $\Delta\phi$

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The Least-Squares Solution:

- Requirement for Applying Least Squares:**
 - All acquisitions have to belong to one single set of interconnected interferograms
- If requirement is met:**
 - $M \geq N$ and A is of rank N
 - In this case solution is found using Least-Squares methods

$$\hat{\phi} = (A^T A)^{-1} A^T \Delta\phi$$
 Normal Equation

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The Small Baseline Subset (SBAS) Method
 How to Calculate $\hat{\phi}_{defo}$ from $\Delta\phi$

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The Singular Value Decomposition (SVD) Approach

- Required** if acquisitions belong to $L > 1$ different interferogram sets
- In the case of $L > 1$,** matrix A is rank deficient (rank: $N - L + 1$) meaning we have less independent observations than unknowns
- Solution through SVD decomposition of A :**
 - $A = USV^T$
 - U : eigenvectors of AA^T , V : Eigenvectors of $A^T A$, and S is matrix of eigenvalues

$$\hat{\phi}_{defo}$$
 is found through: $\hat{\phi}_{defo} = A^* \Delta\phi$ with $A^* = VS^+ U^T$

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The Small Baseline Subset (SBAS) Method
 How To Deal with Nuisance Signals?

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Reminder of the full interferometric phase equation:

$$\Delta\phi = W \left\{ \frac{4\pi}{\lambda} \frac{B_{\perp}}{R \cdot \sin(\theta)} h_{err} + \frac{4\pi}{\lambda} v \cdot \Delta t + \phi_{atmo} + \phi_{orbit} + \phi_{noise} \right\}$$

Target parameters (points to h_{err}) nuisance parameters (points to $\phi_{atmo}, \phi_{orbit}, \phi_{noise}$)

- Also remember that SBAS is operating on unwrapped interferograms \rightarrow **unwrapping errors may occur**
- Hence, the following nuisance signals must be treated in SBAS InSAR:
 - Atmospheric noise ϕ_{atmo}
 - DEM errors $\phi_{h_{err}}$
 - Phase unwrapping errors
 - Orbit errors (ϕ_{orbit}) and noise (ϕ_{noise} ; due to heavy filtering) are largely ignored

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Filtering for Mitigation of Errors

Properties of the phase history ϕ

$$\phi = \underbrace{\phi_{defo}}_{\text{Main interest}} + \underbrace{\phi_{topo} + \phi_{atmo} + \phi_{noise}}_{\text{Nuisance}}$$

ϕ_{defo} : smooth in time (usually)
 ϕ_{topo} : proportional to spatial baseline
 ϕ_{atmo} : random in time – smooth in space
 ϕ_{noise} : random in time and space
 orbit error similar

Separate components based on their temporal, spatial and baseline characteristics

Filtering for Mitigation of Errors

Key idea

- Atmospheric error is smooth in space
- High-pass in space: Subtract spatially smoothed ϕ_s from ϕ
- Atmospheric error is random in time
- Low-pass filter in time: Smooth ϕ in time

ϕ from inversion: $\phi_{defo}, \phi_{atmo}, \dots$ → Filtering → Filtered ϕ mainly ϕ_{defo}

Turbulent tropospheric phase
 Spatially correlated
 But independent between acquisitions

Further Error Mitigation Steps

Tropospheric errors

- Systematic elevation dependence**
Remove based on dependence of phase on elevation
- Regional variability**
Use weather models to mitigate regional trends and stratified elevation-dependent errors

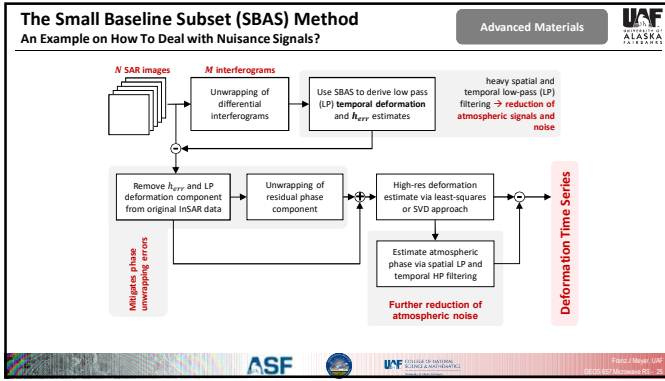
Weather model
 Remove predicted delay

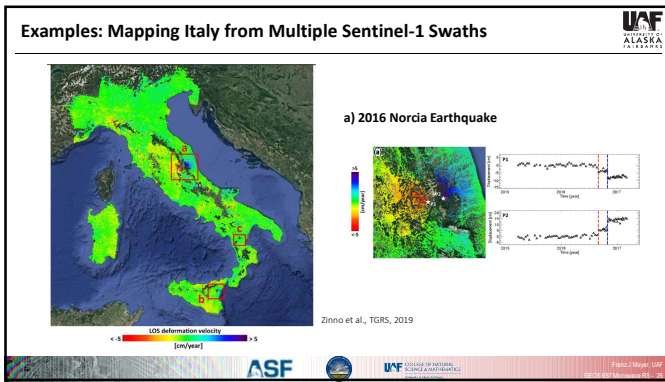
- Large scale
- Stratified

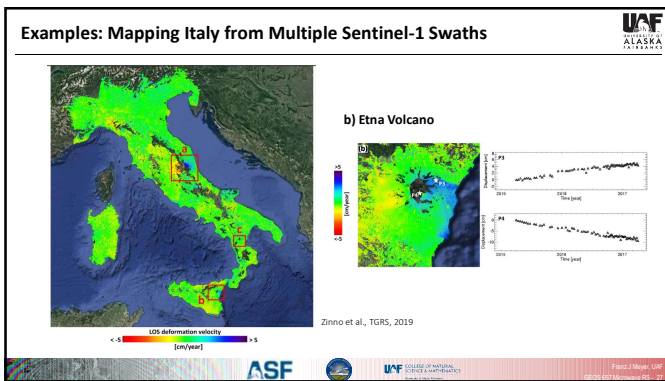
 Jolivet et al., JGR 2014

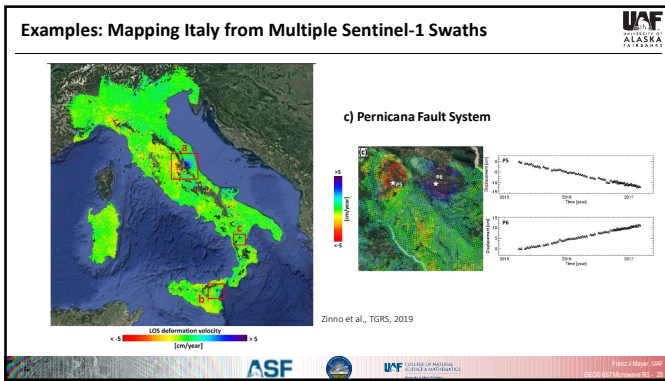
DEM errors
 Exploit dependence on baseline
 Not so critical for small baselines (Sentinel-1) and accurate DEMs

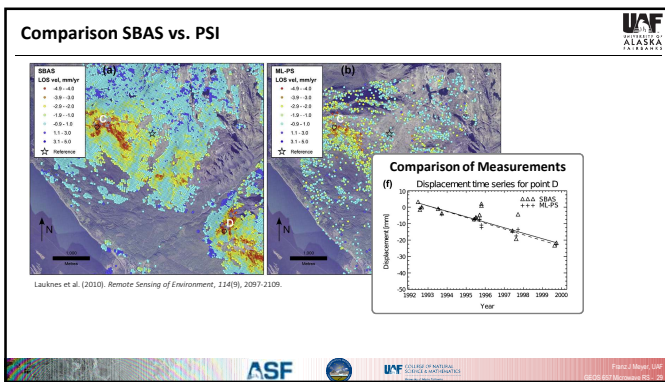
$$\phi_{topo} \sim B_L$$











Advantages and Disadvantages of SBAS

- Advantages:**
 - Usually more coherent points → better description of deformation
 - No motion model required → better for geophysical signals
- Disadvantages:**
 - More noise in the estimates (less accurate compared to PS-InSAR)
 - Spatial averaging → lower spatial resolution
 - More interferograms → significantly higher computational effort
- Other Notes:**
 - SBAS requires that there are no temporal gaps in the time series
 - A deformation model can be integrated into SBAS to constrain the solution. Variations of SBAS that contain models are often referred to as NSBAS (Doin et al., 2011)

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Summary

Input
Time series of SAR images

Processing

- Interferogram formation
- Isolate deformation

Output
Deformation

Point Target InSAR

- + high quality for selected points
- + retains full resolution
- **only few coherent points**
- does not work well for short stacks

Persistent Scatterer Interferometry (PSI)

Distributed Target InSAR

- + **higher point density**
- + flexible, easily applicable to large areas
- usually higher noise level
- averaging reduces resolution

Small Baseline Subset (SBAS)

More about InSAR Time Series Analysis

- InSAR time series analysis is current ongoing research topics
- Many advanced methods have been developed in recent years including:
 - Traditional PS-InSAR (Politecnica di Milano, Italy)
 - StaMPS (Stanford University)
 - DePSI (University of Delft, NL)
 - Coherent Target InSAR (IPTA) (GAMMA Remote Sensing)

Point Target InSAR-Type

- Traditional SBAS InSAR (University of Napoli, Italy)
- StamPS SBAS InSAR (Stanford University)
- GIAN-T (Generic InSAR Analysis Toolbox; <http://earthdef.caltech.edu/projects/giant/wiki>)
- MintPy (Miami InSAR time-series software in Python; <https://github.com/insarlab/MintPy>)

SBAS-Type

- SqueeSAR (TRE, Italy)

Combination of PS and SBAS

- MinTS (Multiscale InSAR Time Series) (CalTec)

Independent Approach

Open Source InSAR Time Series Analysis Software

- Nowadays, there are a number of publicly available open source Time Series Analysis tools available.
- Together with a few community members, we provide coordinated access to these tools via the RadarCODE (Radar COordinated DEvelopment) initiative

Awesome SAR

A curated list of awesome SAR software, libraries, and resources.

Inspired by awesome-python.

- awesome-sar
 - General
 - InSAR Processing Software
 - InSAR Processing Software
 - Time Series Analysis Software
 - Interferometric Phase Correction Software
 - Geospatial Tools
 - Other Resources

Some InSAR Time Series Analysis Literature



- Ferretti, A.; Prati, C.; Rocca, F., "Permanent scatterers in SAR interferometry," *Geoscience and Remote Sensing, IEEE Transactions on* , vol.39, no.1, pp.8-20, Jan 2001
- Lanari, R.; Mora, O.; Manunta, M.; Mallorqui, J.J.; Berardino, P.; Sansosti, E., "A small-baseline approach for investigating deformations on full-resolution differential SAR interferograms," *Geoscience and Remote Sensing, IEEE Transactions on* , vol.42, no.7, pp.1377-1386, July 2004
- Berardino, P.; Fornaro, G.; Lanari, R.; Sansosti, E., "A new algorithm for surface deformation monitoring based on small baseline differential SAR interferograms," *Geoscience and Remote Sensing, IEEE Transactions on* , vol.40, no.11, pp.2375-2383, Nov 2002
- Hooper, A.; Zebker, H.; Segall, P.; Kampes, B., "A new method for measuring deformation on volcanoes and other natural terrains using InSAR persistent scatterers," *Geophysical Research Letters*, 31(23), 2004
- Hooper, A., "A multi-temporal InSAR method incorporating both persistent scatterer and small baseline approaches," *Geophysical Research Letters*, 35, 2008
- Ferretti, A.; Fumagalli, A.; Novelli, F.; Prati, C.; Rocca, F.; Rucci, A., "A New Algorithm for Processing Interferometric Data-Stacks: SqueeSAR," *Geoscience and Remote Sensing, IEEE Transactions on* , vol.49, no.9, pp.3460-3470, Sept. 2011
- Joaquim J. Sousa, Andrew J. Hooper, Ramon F. Hanssen, Luisa C. Bastos, Antonio M. Ruiz, Persistent Scatterer InSAR: A comparison of methodologies based on a model of temporal deformation vs. spatial correlation selection criteria, *Remote Sensing of Environment*, Volume 115, Issue 10, 17 October 2011
- Hetland, E., Musé, P., Simons, M., Lin, Y. N., Agram, P. S., DiCaprio, C. J., "Multiscale InSAR Time Series (MINTS) analysis of surface deformation," *Journal of Geophysical Research: Solid Earth*, 117(B2), 2012



What's Next?



• This is what awaits next:

– Thursday: Lab on SBAS-type InSAR Time Series Analysis using MintPy